



Gateway for integration of Toshiba's air conditioners into KNX
TP-1 (EIB) control systems
Compatible with air conditioners connected through the TCC-Link from Toshiba
Application's Program Version: 3.4

USER MANUAL

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Gateway for integration of Toshiba's air conditioners into KNX TP-1 (EIB) control systems. Compatible with air conditioners connected through the TCC-Link from Toshiba.

Application's Program Version: 3.4

ORDER CODE	LEGACY ORDER CODE
INKNXTOS0160000	TO-AC-KNX-16
INKNXTOS0640000	TO-AC-KNX-64

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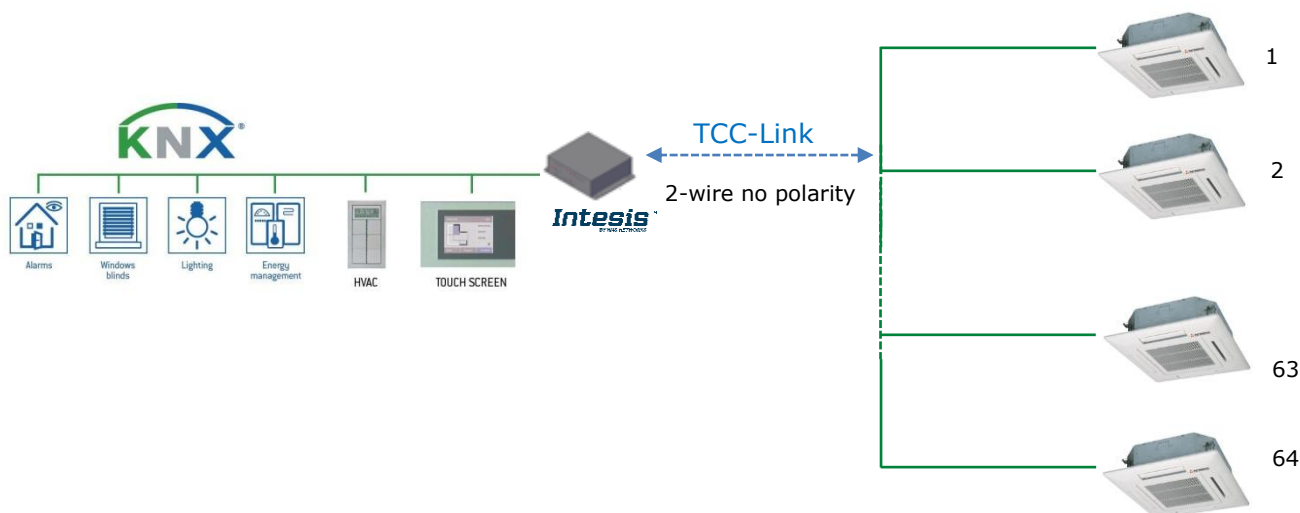
1. Presentation



INKNXTOS---O000 allows a complete and natural integration of TOSHIBA air conditioners with KNX control systems.

Main features:

- Direct connection to Toshiba's TCC-Link bus.
- Multiple objects for control and status (bit, byte, characters...) with KNX standard datapoint types.
- Status objects for every control available.
- Configuration is made directly from ETS. The database of the device comes with a complete set of communication objects, allowing from a simple and quick integration using the basic objects to the most advanced integration with monitoring and control of all the AC unit's parameters.
- Control of the AC unit based on the ambient temperature read by the own AC unit or in the ambient temperature read by any KNX thermostat.
- Total Control and Monitoring of the AC unit from KNX, including monitoring of the AC unit's state of internal variables, error indication, and error code.



2. Connection

2.1 Connection of the INKNXTOS---O000 to the TCC-Link bus:

The INKNXTOS---O000 must be connected directly to the TCC-Link bus of Toshiba. Please, remember to use the ferrites supplied with the device to protect the TCC-Link bus from electromagnetic interferences.

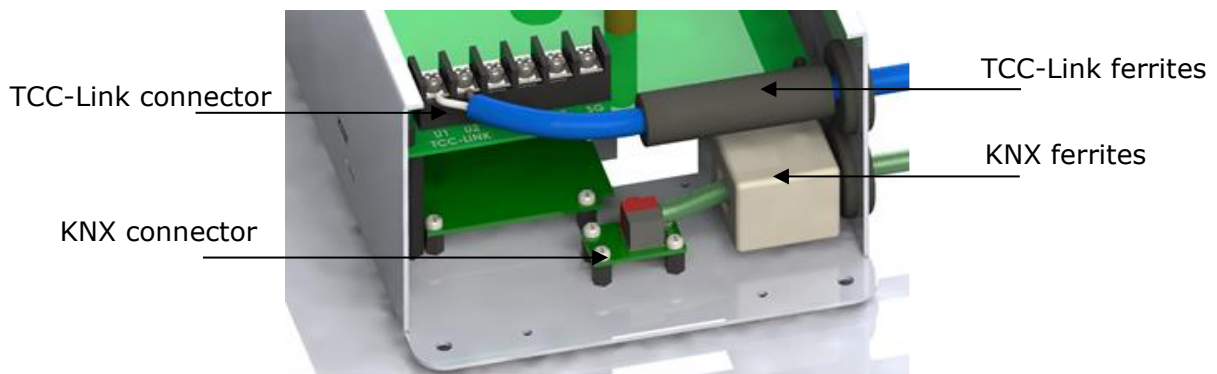


Figure 2.1 INKNXTOS---O000 connection diagrams

2.2 Connection of the INKNXTOS---O000 to the KNX bus:

Disconnect power of the KNX bus. Connect the INKNXTOS---O000 to the KNX TP-1 (EIB) bus using the KNX standard connector (red/grey) of the INKNXTOS---O000, respect polarity.

Reconnect power of the KNX bus, and mains power of the AC unit.

Please, remember to use the ferrites supplied with the device to protect the KNX bus from electromagnetic interferences.

3. Configuration and setup

This is a fully compatible KNX device which must be configured and setup using the ETS standard configuration tool.

The ETS database for this device can be downloaded from:

<https://www.hms-networks.com/p/inknxtos016o000-toshiba-vrf-systems-to-knx-interface>

Please consult the README.txt file, located inside the downloaded zip file, to find instructions on how to install the database.

⚠ Important: Do not forget to select the correct settings of AC indoor unit being connected to the INKNXTOS---O000. This is in "Parameters" of the device in ETS.

4. ETS Parameters

When imported to the ETS software for the first time, the gateway shows the following default parameter configuration:

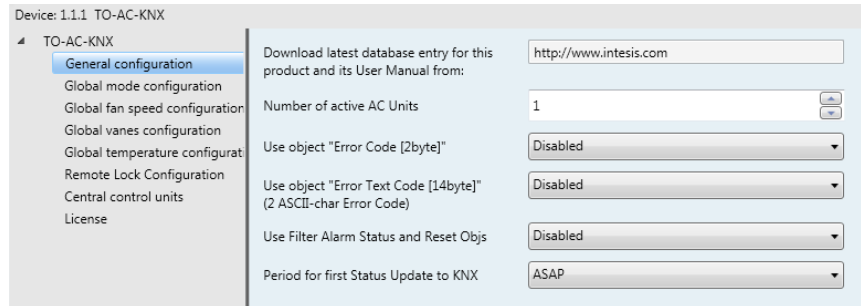


Figure 4.1 Default parameter configuration

With this configuration it's possible to send On/Off (*ACxx Control_ On/Off*), change the AC Mode (*ACxx¹ Control_ Mode*), the Fan Speed (*ACxx Control_ Fan Speed*), the Vanes U-D (*ACxx Control_ Vanes U-D*) and also the Setpoint Temperature (*ACxx Control_ Setpoint Temperature*). The Status_ objects, for the mentioned Control_ objects, are also available to use if needed. Also objects *Status_ AC Return Temp* and *Status_ Error/Alarm* are shown.

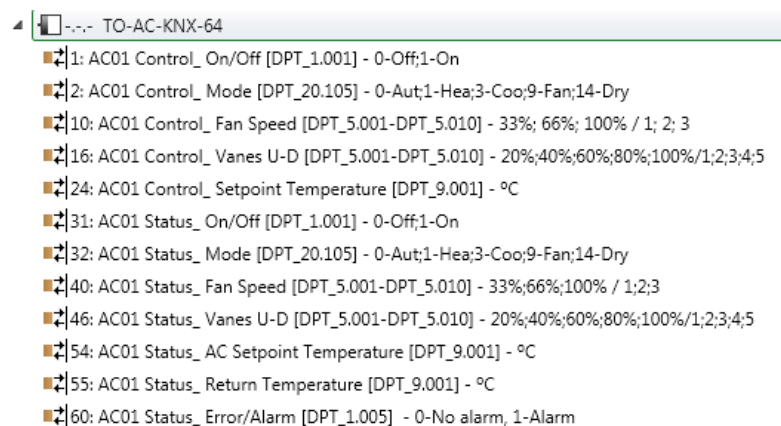


Figure 4.2 Default communication objects

¹ xx corresponds to the AC indoor unit number.

4.1 General configuration dialog

Inside this parameter's dialog it is possible to activate or change the parameters shown in the **Figure 4.1**. The first field shows the URL where to download the database and the user manual for the product.

4.1.1 Number of active AC Units

This parameter is used to select the number of AC units present in the project. Remember that depending on the license you have you can control up to 16 or 64 AC indoor units.

Please check section 4.8 for more information regarding licenses and how to proceed with the activation.

4.1.2 Use object "Error Code [2byte]"

When this parameter is enabled, the Error code communication object will appear, allowing the error codes for each indoor unit to be available for monitoring.

- If set to **"disabled"** the gateway will not show the any action.
- If set to **"enabled"** the *Status_* Error Code will be shown.
 - This object can be read and also sends the indoor unit error, if occurred, in numeric format. If a **"0"** value is shown that means no error.



Figure 4.3 Parameter and communication object detail

4.1.3 Use object "Error Text Code [14byte]"

This parameter shows/hide the *Status_ Error Text* communication object which describes the error code as it is displayed in the Toshiba's bus.

- If set to **"disabled"** the gateway will not show the any action.
- If set to **"enabled"** the *Status_* Error Code will be shown.
 - This object can be read and also sends the indoor unit error, if occurred, in text format. The errors shown have the same format as at the remote controller and at the error list from the indoor unit manufacturer. If the object's value is empty that means no error.

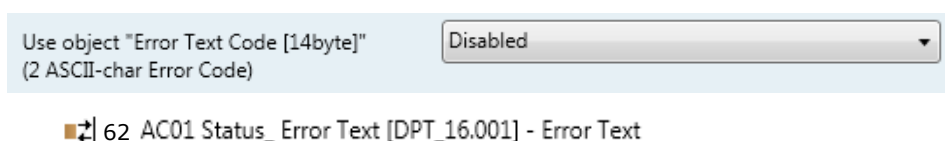


Figure 4.4 Parameter and communication object detail

4.1.4 Use filter alarm Status and Reset Objs

This parameter shows/hides *Control_ Reset Filter* and *Status_ Filter Alarm* that lets reset the filter status and also monitor if there is a filter alarm.

- ↕ 27 AC01 Control_ Reset Filter [DPT_1.015] - 1-Reset filter
- ↕ 56 AC01 Status_ Filter Alarm [DPT_1.005] - 0-No alarm;1-Alarm

- If set to **"no"** the object will not be shown.
- If set to **"yes"** the *Control_ Reset Filter* y *Status_ Filter Alarm* objects will appear.
 - The *Status_* object will show a **"0"** value when there's no filter alarm, and a **"1"** value when the filter is full. Once the filter is cleaned, the alarm can be reset by sending a **"1"** value to the *Control_ Reset Filter* object.

4.1.5 Period for first status update to KNX

This parameter defines how fast the status is updated to KNX. Depending on the value selected, more or less priority will be assigned to this action. As there are so many parameters available, it is important to consider carefully how to set this parameter.

- If set to **"ASAP"**, all status communication objects will send its value (if needed).
- If set to **"Slow"**, all status communication objects will send its value (if needed), but slower than in the previous option (ASAP).
- If set to **"Super Slow"**, all status communication objects will send its value (if needed), but slower than in the previous option (Slow).

4.2 Global Mode Configuration dialog

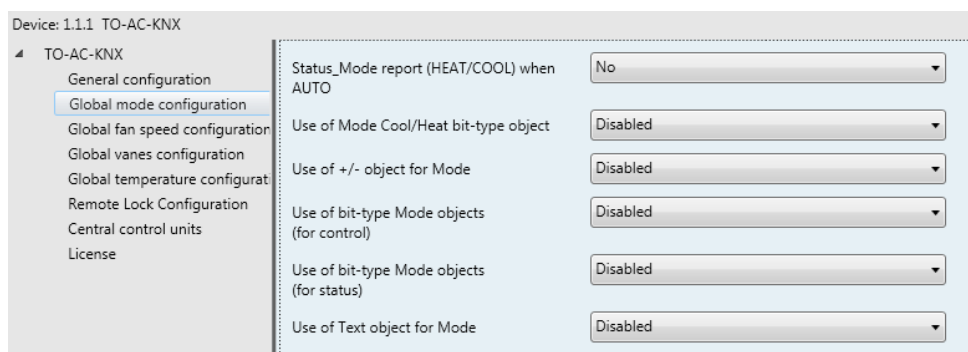


Figure 4.6 Default Mode Configuration dialog

All the parameters in this section are related with the different mode properties and communication objects.

- ↕ 2 AC01 Control_ Mode [DPT_20.105] - 0-Aut;1-Hea;3-Coo;9-Fan;14-Dry

The byte-type communication object for Mode works with the DTP_20.105. Auto mode will be enabled with a "0" value, Heat mode with a "1" value, Cool mode with a "3" value, Fan mode with a "9" value and Dry mode with a "14" value.

4.2.1 Status_ Mode report (HEAT/COOL) when auto

This parameter is used to indicate if the indoor unit reports if the AC system is working on Heat or Cool mode when it is in auto mode.

- If set to "no", the sistem is not reporting the working mode when on auto.
- If set to "yes", the sistem is reports the working mode when on auto.

4.2.2 Use of Mode Cool/Heat bit-type object

This parameter shows/hides the *Control_* and *Status_ Mode Cool/Heat* communication objects.

```

■ ↕ 3 AC01 Control_ Mode Cool/Heat [DPT_1.100] - 0-Cool; 1-Heat
■ ↕ 33 AC01 Status_ Mode Cool/Heat [DPT_1.100] - 0-Cool; 1-Heat

```

- If set to "no" the objects will not be shown.
- If set to "yes" the *Control_* and *Status_ Mode Cool/Heat* objects will appear.
 - When a "1" value is sent to the *Control_* communication object, **Heat mode** will be enabled in the indoor unit, and the *Status_* object will return this value.
 - When a "0" value is sent to the *Control_* communication object, **Cool mode** will be enabled in the indoor unit, and the *Status_* object will return this value.

4.2.3 Use of + / - object for Mode

This parameter shows/hides the *Control_ Mode +/-* communication object which lets change the indoor unit mode by using two different datapoint types.

```

■ ↕ 9 AC01 Control_ Mode +/- [DPT_1.007-DPT_1.008] - 0-Dec.;1-Inc. / 0-Up;1-Down

```

- If set to "no" the object will not be shown.
- If set to "yes" the *Control_ Mode +/-* object and a new parameter will appear.

Enable use of +/- object for Mode	yes
> DPT type for +/- Mode Object	0-Up / 1-Down [DPT_1.008]

Figure 4.7 Parameter detail

➤ DPT type for +/- Mode Object

This parameter lets choose between the datapoints **0-Up / 1-Down [DPT_1.008]** and **0-Decrease / 1-Increase [DPT_1.007]** for the *Control_Mode* +/- object.

The sequence followed when using this object is shown below:



- Up / Increase
- Down / Decrease

⚠ **Important:** Read the documentation of your indoor unit to check if it has HEAT mode available.

4.2.4 Enable use of bit-type Mode objects (for control)

This parameter shows/hides the bit-type *Control_Mode* objects.

- ↕ 4 AC01 Control_Mode Auto [DPT_1.002] - 1-Set AUTO mode
- ↕ 5 AC01 Control_Mode Heat [DPT_1.002] - 1-Set HEAT mode
- ↕ 6 AC01 Control_Mode Cool [DPT_1.002] - 1-Set COOL mode
- ↕ 7 AC01 Control_Mode Fan [DPT_1.002] - 1-Set FAN mode
- ↕ 8 AC01 Control_Mode Dry [DPT_1.002] - 1-Set DRY mode

- If set to **"no"** the objects will not be shown.
- If set to **"yes"** the *Control_Mode* objects for Auto, Heat, Cool, Fan and Dry will appear. To activate a mode by using these objects a **"1"** value has to be sent.

4.2.5 Use of bit-type Mode objects (for status)

This parameter shows/hides the bit-type *Status_Mode* objects.

- ↕ 34 AC01 Status_Mode Auto [DPT_1.002] - 1-Set AUTO mode
- ↕ 35 AC01 Status_Mode Heat [DPT_1.002] - 1-Set HEAT mode
- ↕ 36 AC01 Status_Mode Cool [DPT_1.002] - 1-Set COOL mode
- ↕ 37 AC01 Status_Mode Fan [DPT_1.002] - 1-Set FAN mode
- ↕ 38 AC01 Status_Mode Dry [DPT_1.002] - 1-Set DRY mode

- If set to **"no"** the objects will not be shown.
- If set to **"yes"** the *Status_Mode* objects for Auto, Heat, Cool, Fan and Dry will appear. When enabled, a mode will return a **"1"** through its bit-type object.

4.2.6 Use of Text object for Mode

This parameter shows/hides the *Status_ Mode Text* communication object.

39 AC01 Status_ Mode Text [DPT_16.001] - Mode Text

- If set to **“no”** the object will not be shown.
- If set to **“yes”** the *Status_ Mode Text* object will appear. Also, in the parameters, will be shown five text fields, one for each mode, that will let modify the text string displayed by the *Status_ Mode Text* when changing mode.

> String when mode is AUTO	AUTO
> String when mode is HEAT (if available)	HEAT
> String when mode is COOL	COOL
> String when mode is FAN	FAN
> String when mode is DRY	DRY

Figure 4.8 Parameter detail

4.3 Global Fan Speed Configuration dialog

Device: 1.1.1 TO-AC-KNX

- TO-AC-KNX
 - General configuration
 - Global mode configuration
 - Global fan speed configuration
 - Global vanes configuration
 - Global temperature configurati
 - Remote Lock Configuration
 - Central control units
 - License

Configuration options:

- DPT object type for fan speed: Scaling [DPT_5.001]
- Use Auto/Manual fan speed Object: Disabled
- Use of +/- object for fan speed: Disabled
- Use of bit-type fan speed objects (for control): Disabled
- Use of bit-type fan speed objects (for status): Disabled
- Use of Text object for fan speed: Disabled

Figure 4.9 Fan Speed Configuration dialog

All the parameters in this section are related with the Fan Speed properties and communication objects.

4.3.1 DPT object type for fanspeed

With this parameter it is possible to change the DPT for the *Control_ Fan Speed* and *Status_ Fan Speed* byte-type communication objects. Datapoints Scaling (DPT_5.001) and Enumerated (DPT_5.010) can be selected.

⚠ Important: *The communication objects shown in this section may be different depending on the number of fan speeds available, although they all share the same communication object number.*

- When “**Enumerated [DPT 5.010]**” is selected, *Control_ Fan Speed* and *Status_ Fan Speed* communication objects for this DPT will appear.

- ↕ 10 AC01 Control_ Fan Speed [DPT_5.010] - 1;2;3
- ↕ 40 AC01 Status_ Fan Speed [DPT_5.010] - 1;2;3

The first fan speed will be selected if a “**1**” is sent to the *Control_* object. The second one will be selected sending a “**2**”; the third one will be selected sending a “**3**”.

The *Status_* object will always return the value for the fan speed selected.

⚠ **Important:** If a “**0**” value is sent to the *Control_* object, the minimum fan speed will be selected. If a value bigger than “**3**” is sent to the *Control_* object, then the maximum fan speed will be selected.

- When “**Scaling [DPT 5.001]**” is selected, *Control_ Fan Speed* and *Status_ Fan Speed* communication objects for this DPT will appear.

- ↕ 10 AC01 Control_ Fan Speed [DPT_5.001] - 33%;66%;100%
- ↕ 40 AC01 Status_ Fan Speed [DPT_5.001] - 33%;66%;100%

The next table shows the range of values that can be sent through the *Control_* object and the value returned by the *Status_* object.

	Fan Speed 1	Fan Speed 2	Fan Speed 3
Control_	0% - 33%	34% - 66%	67% - 100%
Status_	33%	66%	100%

⚠ **Important:** Read the documentation of your indoor unit to check how many fan speeds are available.

4.3.2 Use Auto/Manual Fanspeed objects (for Control and Status)

This parameter shows/hides the bit-type *Control_ Fan Speed Man/Auto* and the *Status_ Fan Speed Man/Auto* objects.

- ↕ 11 AC01 Control_ Fan Speed Man/Auto [DPT_1.002] - 0-Manual;1-Auto
- ↕ 41 AC01 Status_ Fan Speed Man/Auto [DPT_1.002] - 0-Manual;1-Auto

4.3.3 Enable use of +/- object for Fan Speed

This parameter shows/hides the *Control_ Fan Speed +/-* communication object which lets increase/decrease the indoor unit fan speed by using two different datapoint types.

- ↕ 15 AC01 Control_ Fan Speed +/- [DPT_1.008] - 0-Up;1-Down

- If set to **“no”** the object will not be shown.
- If set to **“yes”** the *Control_ Fan Speed +/-* object and a new parameter will appear.

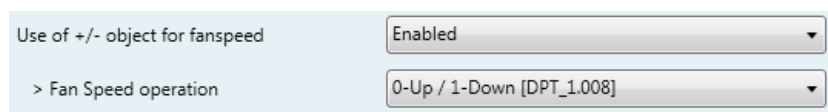


Figure 4.13 Parameter detail

➤ Fan Speed operation

This parameter lets choose between the datapoints **0-Up / 1-Down [DPT_1.008]** and **0-Decrease / 1-Increase [DPT_1.007]** for the *Control_ Fan Speed +/-* object.

4.3.4 Use of bit-type Fan Speed objects (for Control)

This parameter shows/hides the bit-type *Control_ Fan Speed* objects.

- ↔ 12 Control_ Fan Speed 1 [DPT_1.002 - 1bit] - 1-Set Fan Speed 1
- ↔ 13 Control_ Fan Speed 2 [DPT_1.002 - 1bit] - 1-Set Fan Speed 2
- ↔ 14 Control_ Fan Speed 3 [DPT_1.002 - 1bit] - 1-Set Fan Speed 3

- If set to **“no”** the objects will not be shown.
- If set to **“yes”** the *Control_ Fan Speed* objects for Speed 1, Speed 2 and Speed 3 will appear. To activate a Fan Speed by using these objects a **“1”** value has to be sent.

4.3.5 Enable use of bit-type Fan Speed objects (for Status)

This parameter shows/hides the bit-type *Status_ Fan Speed* objects.

- ↔ 42 AC01 Status_ Fan Speed 1 [DPT_1.002] - 1-Set Fan Speed 1
- ↔ 43 AC01 Status_ Fan Speed 2 [DPT_1.002] - 1-Set Fan Speed 2
- ↔ 44 AC01 Status_ Fan Speed 3 [DPT_1.002] - 1-Set Fan Speed 3

- If set to **“no”** the objects will not be shown.
- If set to **“yes”** the *Status_ Fan Speed* objects for Speed 1, Speed 2 and Speed 3 will appear. When a Fan Speed is enabled, a **“1”** value is returned through its bit-type object.

4.3.6 Enable use of Text object for Fan Speed

This parameter shows/hides the *Status_ Fan Speed Text* communication object.

- ↔ 45 AC01 Status_ Fan Speed Text [DPT_16.001] - Fan Speed Text

- If set to **“no”** the object will not be shown.

- If set to **“yes”** the *Status_ Fan Speed Text* object will appear. Also, in the parameters, will be shown five text fields, one for each Fan Speed, that will let modify the text string displayed by the *Status_ Fan Speed Text* when changing a fan speed.

> String when fan speed is 1	SPEED 1
> String when fan speed is 2	SPEED 2
> String when fan speed is 3	SPEED 3
> String when fan speed is AUTO	AUTO

Figure 4.14 Parameter detail

4.4 Global Vanes Configuration dialog

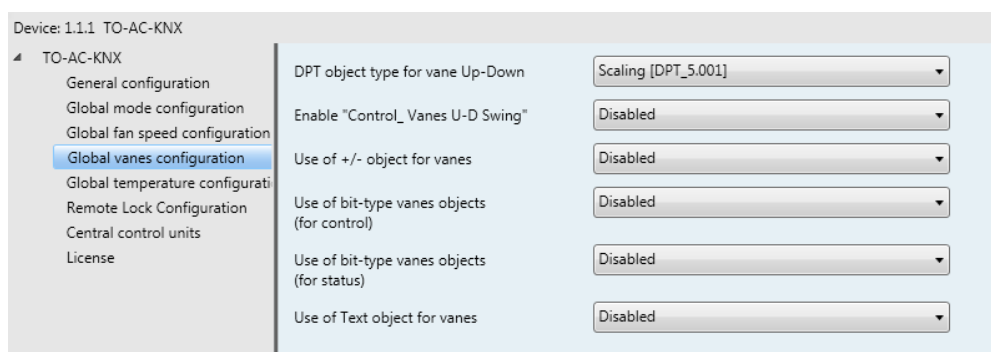


Figure 4.15 Vanes Up-Down Configuration dialog

All the parameters in this section are related with the Vanes Up-Down properties and communication objects.

4.4.1 DPT object type for Vanes Up-Down

With this parameter it is possible to change the DPT for the *Control_ Vanes U-D* and *Status_ Vanes U-D* byte-type communication objects. Datapoints Scaling (DPT_5.001) and Enumerated (DPT_5.010) can be selected.

⚠ Important: *The communication objects shown in this section may be different depending on the number of vanes position available, although they all share the same communication object number.*

- When **“Enumerated [DPT 5.010]”** is selected, *Control_ Vanes U-D* and *Status_ Vanes U-D* communication objects for this DPT will appear.

```

■ ↕ 16 AC01 Control_ Vanes U-D [DPT_5.001] - 20%;40%;60%;80%;100%
■ ↕ 46 AC01 Status_ Vanes U-D [DPT_5.001] - 20%;40%;60%;80%;100%

```

To choose a vanes position, values from **“1”** to **“5”** can be sent to the *Control_* object. Each value will correspond to the position (i.e. Value **“3”** = Position 3).

The *Status_* object will always return the value for the vane position selected.

⚠ **Important:** If a "0" value is sent to the *Control_* object, the Position 1 will be selected. If a value bigger than "5" is sent to the *Control_* object, then the higher Position will be selected.

- When "Scaling [DPT 5.001]" is selected, *Control_ Vane Up-Down* and *Status_ Vane Up-Down* communication objects for this DPT will appear.

- ↕ 16 *Control_ Vanes U-D / 5 Pos* [DPT_5.001 - 1byte] - Thresholds:30%,50%,70% and 90%
- ↕ 46 *Status_ Vanes U-D / 5 Pos* [DPT_5.001 - 1byte] - 20%, 40%, 60%, 80% and 100%

The next table shows the range of values that can be sent through the *Control_* object and the value returned by the *Status_* object.

	Vanes Pos.1	Vanes Pos.2	Vanes Pos.3	Vanes Pos.4	Vanes Pos.5
<i>Control_</i>	0% - 20%	21% - 40%	41% - 60%	61% - 80%	81% - 100%
<i>Status_</i>	20%	40%	60%	80%	100%

4.4.2 Enable "Control_ Vanes U-D Swing"

This parameter lets choose if the unit has any of the two available modes for vanes directions.



Figure 4.16 Parameter detail

- If set to "Disabled" all the parameters and communication objects for the for the 5 Vanes positions will not be shown and communication objects only for SWING and STANDBY will be shown.
- If set to "Enabled" all the parameters and communication objects (if enabled in the parameters dialog) for the swing positions will be shown.

- ↕ 17 *Control_ Vanes U-D Swing* [DPT_1.002 - 1bit] - 0-Off;1-Swing
- ↕ 47 *Status_ Vanes U-D Swing* [DPT_1.002 - 1bit] - 0-Off;1-Swing

⚠ **Important:** Read the documentation of your indoor unit to check if Up-Down Vanes Swing is available.

4.4.3 Enable use of +/- object for Vanes U-D

This parameter shows/hides the *Control_ Vane Up-Down +/-* communication object which lets change the indoor unit vane position by using two different datapoint types.

■↕ 23 Control_ Vanes U-D +/- [DPT_1.007 - 1bit] - 0-Decrease;1-Increase

- If set to **"no"** the object will not be shown.
- If set to **"yes"** the *Control_ Vanes U-D +/-* object and a new parameter will appear.

The screenshot shows a configuration interface with two dropdown menus. The first dropdown is labeled 'Use of +/- object for vanes' and is set to 'Enabled'. The second dropdown is labeled '> Vane UD operation' and is set to '0-Decrease / 1-Increase [DPT_1.007]'.

Figure 4.17 Parameter detail

➤ Vane UD operation

This parameter lets choose between the datapoints **0-Up / 1-Down [DPT_1.008]** and **0-Decrease / 1-Increase [DPT_1.007]** for the *Control_ Vanes U-D +/-* object.

4.4.4 Enable use of bit-type Vane U-D objects (for Control)

This parameter shows/hides the bit-type *Control_ Vanes U-D* objects.

■↕ 18 Control_ Vanes U-D Pos 1 [DPT_1.002 - 1bit] - 1-Set Position 1
 ■↕ 19 Control_ Vanes U-D Pos 2 [DPT_1.002 - 1bit] - 1-Set Position 2
 ■↕ 20 Control_ Vanes U-D Pos 3 [DPT_1.002 - 1bit] - 1-Set Position 3
 ■↕ 21 Control_ Vanes U-D Pos 4 [DPT_1.002 - 1bit] - 1-Set Position 4
 ■↕ 22 Control_ Vanes U-D Pos 5 [DPT_1.002 - 1bit] - 1-Set Position 5

- If set to **"no"** the objects will not be shown.
- If set to **"yes"** the *Control_ Vanes U-D* objects for each Position will appear. To activate a Vanes Position by using these objects, a **"1"** value has to be sent.

4.4.5 Enable use of bit-type Vane U-D objects (for Status)

This parameter shows/hides the bit-type *Status_ Vanes U-D* objects.

■↕ 48 Status_ Vanes U-D Pos 1 [DPT_1.002 - 1bit] - 1-Vanes in Position 1
 ■↕ 49 Status_ Vanes U-D Pos 2 [DPT_1.002 - 1bit] - 1-Vanes in Position 2
 ■↕ 50 Status_ Vanes U-D Pos 3 [DPT_1.002 - 1bit] - 1-Vanes in Position 3
 ■↕ 51 Status_ Vanes U-D Pos 4 [DPT_1.002 - 1bit] - 1-Vanes in Position 4
 ■↕ 52 Status_ Vanes U-D Pos 5 [DPT_1.002 - 1bit] - 1-Vanes in Position 5

- If set to **"no"** the objects will not be shown.

- If set to **“yes”** the *Status_ Vanes U-D* objects for each Position will appear. When a Vanes Position is enabled, a **“1”** value is returned through its bit-type object.

4.4.6 Enable use of Text object for Vane U-D

This parameter shows/hides the *Status_ Vanes U-D Text* communication object.

53 Status_ Vanes U-D Text [DPT_16.001 - 14byte] - ASCII String

- If set to **“no”** the object will not be shown.
- If set to **“yes”** the *Status_ Vanes U-D Text* object will appear. Also, in the parameters will be shown seven text fields, five for the Vane Position and one for the Auto function and another one for the Swing function, that will let modify the text string displayed by the *Status_ Vanes U-D Text* when changing a vane position.

> String when vanes U-D is in POS1	U-D POS1
> String when vanes U-D are in POS2	U-D POS2
> String when vanes U-D are in POS3	U-D POS3
> String when vanes U-D are in POS4	U-D POS4
> String when vanes U-D are in POS5	U-D POS5
> String when vanes U-D are in SWING	U-D SWING
> String when vanes U-D are in STOP	U-D STOP

Figure 4.19 Parameter detail

4.5 Global Temperature Configuration dialog

Device: 1.1.1 TO-AC-KNX

TO-AC-KNX

- General configuration
- Global mode configuration
- Global fan speed configuration
- Global vanes configuration
- Global temperature configuration
- Remote Lock Configuration
- Central control units
- License

Use of +/- object for Setpoint Temp. Disabled ▼

Ambient temp.ref. is provided from KNX
(carefully read User Guide if enabled) Disabled ▼

Figure 4.20 Default Temperature Configuration dialog

All the parameters in this section are related with the Temperature properties and communication objects.

4.5.1 Enable use of +/- object for Setpoint Temp

This parameter shows/hides the *Control_ Setpoint Temp +/-* communication object which lets change the indoor unit setpoint temperature by using two different datapoint types.

■ ↕ 25 Control_ Setpoint Temp +/- [DPT_1.007 - 1bit] - 0-Decrease;1-Increase

- If set to **"no"** the object will not be shown.
- If set to **"yes"** the *Control_ Setpoint Temp +/-* object and a new parameter will appear.

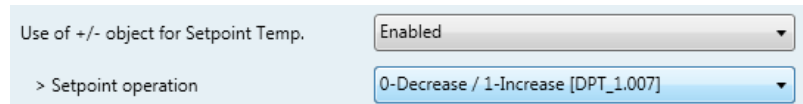






Figure 4.22 Parameter detail

➤ Setpoint operation

This parameter lets choose between the datapoints **0-Up / 1-Down [DPT_1.008]** and **0-Decrease / 1-Increase [DPT_1.007]** for the *Control_ Setpoint Temp +/-* object.

(Lower limit) **18°C**  19°C  ...  28°C  **27°C** (Upper limit)

- Up / Increase
- Down / Decrease

4.5.2 Ambient temp. ref. is provided from KNX

This parameter shows/hides the *Control_ Ambient Temperature* communication object which lets use an ambient temperature reference provided by a KNX device.

■ ↕ 26 Control_ Ambient Temperature [DPT_9.001 - 2byte] - (°C)

- If set to **"no"** the object will not be shown.
- If set to **"yes"** the *Control_ Ambient Temperature* object will appear. Meant to be enabled when you want the temperature provided by a KNX sensor to be the reference ambient temperature for the air conditioner. Then, the following formula applies for calculation of real *Control_ Setpoint Temperature* sent to the AC unit:

$$\text{"AC Setp. Temp"} = \text{"AC Ret. Temp"} - (\text{"KNX Amb. Temp."} - \text{"KNX Setp. Temp"})$$

- AC Setp. Temp: AC indoor unit setpoint temperature
- AC Ret. Temp: AC indoor unit return temperature
- KNX Amb. Temp.: Ambient temperature provided from KNX
- KNX Setp. Temp: Setpoint temperature provided from KNX

As an example, consider the following situation:

User wants: **19°C** ("KNX Setp. Temp.")

User sensor (a KNX sensor) reads: **21°C** ("KNX Amb Temp.")

Ambient temp. read by Toshiba system is: **24°C** ("AC Ret. Temp")

In this example, the final setpoint temperature that INKNXTOS---0000 will send out to the indoor unit (shown in "Setp. Temp.") will become $24^{\circ}\text{C} - (21^{\circ}\text{C} - 19^{\circ}\text{C}) = 22^{\circ}\text{C}$. This is the setpoint that will actually be requested to Toshiba unit.

This formula will be applied as soon as the *Control_Setpoint Temperature* and *Control_Ambient Temperature* objects are written at least once from the KNX installation. After that, they are kept always consistent.

Note that this formula will always drive the AC indoor unit demand in the *right* direction, regardless of the operation mode (Heat, Cool or Auto).

4.6 Remote Lock Configuration

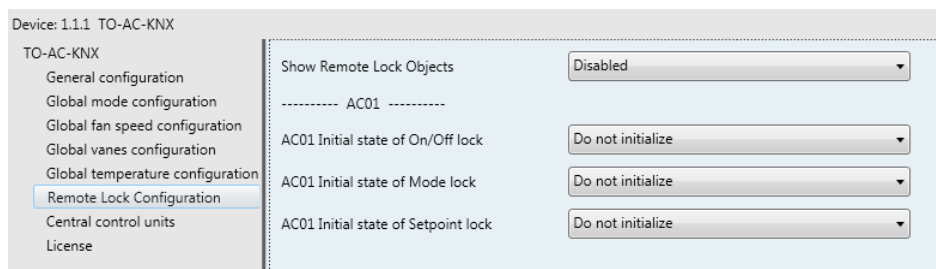


Figure 4.24 Parameter detail

All the parameters in this section are related to each AC unit and its Remote Control commands.

4.6.1 Show Remote Lock Objects

This parameter is used to show or hide the remote lock objects related to each indoor unit.

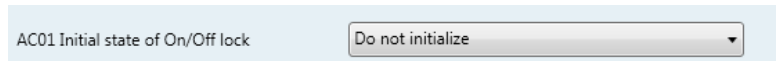
- ↔ 28 AC01 Control_ Remote Lock On/Off [DPT_1.003] - 0-Disable;1-Enable
- ↔ 29 AC01 Control_ Remote Lock Mode [DPT_1.003] - 0-Disable;1-Enable
- ↔ 30 AC01 Control_ Remote Lock Setp Temp [DPT_1.003] - 0-Disable;1-Enable

- ↔ 57 AC01 Status_ Remote Lock On/Off [DPT_1.003] - 0-Disable;1-Enable
- ↔ 58 AC01 Status_ Remote Lock Mode [DPT_1.003] - 0-Disable;1-Enable
- ↔ 59 AC01 Status_ Remote Lock Setpoint Temp [DPT_1.003] - 0-Disable;1-Enat

Figure 4.24 Communication objects shown regarding Remote Lock Objects

4.6.2 ACxx Initial state of On/Off lock

This parameter is used to define if the remote controller of the AC system is capable of controlling the On/Off function on start.



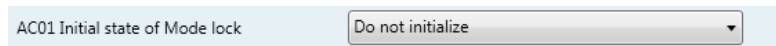
The screenshot shows a light blue header bar with the text 'AC01 Initial state of On/Off lock' on the left and a dropdown menu on the right. The dropdown menu is currently set to 'Do not initialize'.

Figure 4.25 Parameter detail

- If set to **“Do not initialize”**, the remote controller of the AC system will be set into its last status regarding the On/Off lock function.
- If set to **“Start unlocked”**, the remote controller of the AC system will be able to command the On/Off order of the AC unit.
- If set to **“Start locked”**, the remote controller of the AC system will not be able to command the On/Off order of the AC unit.

4.6.3 ACxx Initial state of Mode lock

This parameter is used to define if the remote controller of the AC system is capable of controlling the current Mode.



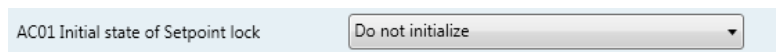
The screenshot shows a light blue header bar with the text 'AC01 Initial state of Mode lock' on the left and a dropdown menu on the right. The dropdown menu is currently set to 'Do not initialize'.

Figure 4.27 Parameter detail

- If set to **“Do not initialize”**, the remote controller of the AC system will be set into its last status regarding the Mode lock function.
- If set to **“Start unlocked”**, the remote controller of the AC system will be able to command the current mode of the AC unit.
- If set to **“Start locked”**, the remote controller of the AC system will not be able to command the current mode of the AC unit.

4.6.4 ACxx Initial state of Setpoint lock

This parameter is used to define if the remote controller of the AC system is capable of controlling the Setpoint temperature.



The screenshot shows a light blue header bar with the text 'AC01 Initial state of Setpoint lock' on the left and a dropdown menu on the right. The dropdown menu is currently set to 'Do not initialize'.

Figure 4.28 Parameter detail

- If set to **“Do not initialize”**, the remote controller of the AC system will be set into its last status regarding the Mode lock function.
- If set to **“Start unlocked”**, the remote controller of the AC system will be able to command the Setpoint temperature of the AC unit.

- If set to **“Start locked”**, the remote controller of the AC system will not be able to command the Setpoint temperature of the AC unit.

4.7 Central Control units

This parameter is used to change the Central Control address of the AC units. Use this parameter if you need to change the by default addressing of the Central Control addresses for each indoor unit to match any specification of the AC system integrator.

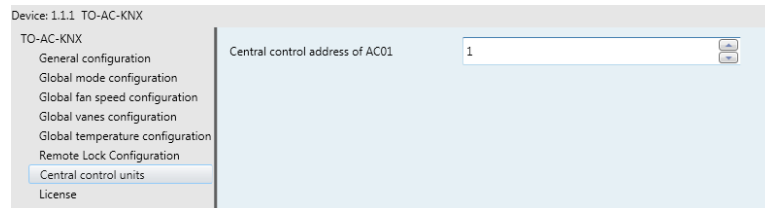


Figure 4.29 Parameter detail

4.8 License

This field must be used only if you need to move from the TO-AC-KNX-16 to the TO-AC-KNX-64 version. Please, contact our sales department to ask for a license upgrade.

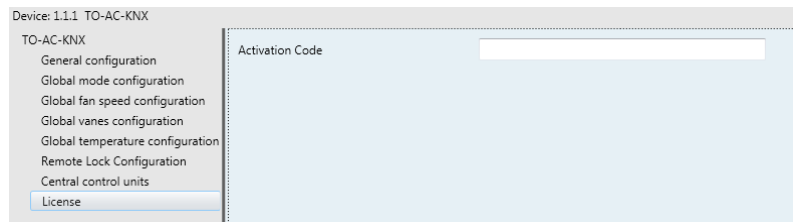


Figure 4.30 Parameter detail

5. Specifications



Housing	Industrial sheet metal Size: 217 mm × 147 mm × 90 mm Weight: 1.500 Kg
Color	Gray metalized
Power	100 to 240VAC~ 50 to 60 Hz 5W max Power connector: C14 (male) ²
Fuse	250 V 1.5 A Dimensions: 20 × 5 mm
Terminal wiring (for low-voltage signals)	Per terminal: solid wires or stranded wires (twisted or with ferrule) One core: 0.75mm ² ... 1.25mm ² Two cores: 0.75mm ² ... 1.25mm ² Three cores: Not permitted
Mounting	Wall
KNX port	1 × KNX TP1 (EIB) opto-isolated (Plug-in screw terminal block 2 poles)
TCC-LINK port	1 × TCC-LINK connector (Plug-in screw terminal block 2 poles "U1" "U2"). SELV
LED indicators	5 × Toshiba Interface (POWER, RS485, TCC-LINK, ERROR, TEST) 1 × KNX port link and activity
Push buttons	1 × KNX programming button
Operational temperature range	0°C to +40°C
Operational humidity range	5% to 95%, non-condensing
Protection	IP20 (IEC60529)
RoHS conformity	Compliant with RoHS directive (2002/95/CE)
Norms and standards	CE conformity to EMC directive (2004/108/EC) and Low-voltage directive (2006/95/EC) EN 61000-6-1 ; EN 61000-6-3 ; EN 60950-1 ; EN 50491-3

² A 1.6 meters long power cable with a C14 male connector is supplied with the device.

6. AC Unit Types compatibility

A list of Toshiba indoor unit model references compatible with INKNXTOS---O000 and their available features can be found in:

https://www.hms-networks.com/docs/default-source/products/intesis/manuals-and-guides--reference-guides/intesis_inxxtos001rx00_compatibility-list.pdf

7. Error Codes

Please, check the error code of your AC system for more information or contact your nearest Toshiba technical support service.

8. Appendix A – Communication Objects Table

TOPIC	OBJECT NUMBER	NAME	LENGTH	DATAPOINT TYPE		FLAGS				FUNCTION
				DPT_NAME	DPT_ID	R	W	T	U	
On/Off	1	ACxx Control_ On/Off	1 bit	DPT_Switch	1.001		W	T		0 - Off; 1-On
Mode	2	ACxx Control_ Mode	1 byte	DPT_HVACContrMode	20.105		W	T		0 - Auto; 1 - Heat; 3 - Cool; 9 - Fan; 14 - Dry
	3	ACxx Control_ Mode Cool/Heat	1 bit	DPT_Heat/Cool	1.100		W	T		0 - Cool; 1 - Heat;
	4	ACxx Control_ Mode Auto	1 bit	DPT_Bool	1.002		W	T		1 - Auto
	5	ACxx Control_ Mode Heat	1 bit	DPT_Bool	1.002		W	T		1 - Heat
	6	ACxx Control_ Mode Cool	1 bit	DPT_Bool	1.002		W	T		1 - Cool
	7	ACxx Control_ Mode Fan	1 bit	DPT_Bool	1.002		W	T		1 - Fan
	8	ACxx Control_ Mode Dry	1 bit	DPT_Bool	1.002		W	T		1 - Dry
	9	ACxx Control_ Mode +/-	1 bit	DPT_Step	1.007		W			0 - Decrease; 1 - Increase
		ACxx Control_ Mode +/-	1 bit	DPT_UpDown	1.008		W			0 - Up; 1 - Down
Fan Speed	10	ACxx Control_ Fan Speed / 3 Speeds	1 byte	DPT_Scaling	5.001		W	T		0%-49% - Speed 1; 50%-82% - Speed 2; 83%-100% - Speed 3;
		ACxx Control_ Fan Speed / 3 Speeds	1 byte	DPT_Enumerated	5.010		W	T		1 - Speed 1; 2 - Speed 2; 3 Speed 3;
	11	ACxx Control_ Fan Speed Man/Auto	1 bit	DPT_Bool	1.002		W	T		0 - Manual; 1 - Auto
	12	ACxx Control_ Fan Speed 1	1 bit	DPT_Bool	1.002		W	T		1 - Set Fan Speed 1
	13	ACxx Control_ Fan Speed 2	1 bit	DPT_Bool	1.002		W	T		1 - Set Fan Speed 2
	14	ACxx Control_ Fan Speed 3	1 bit	DPT_Bool	1.002		W	T		1 - Set Fan Speed 3
	15	ACxx Control_ Fan Speed +/-	1 bit	DPT_Step	1.007		W			0 - Decrease; 1 - Increase
ACxx Control_ Fan Speed +/-		1 bit	DPT_UpDown	1.008		W			0 - Up; 1 - Down	
Vanes Up-Down	16	ACxx Control_ Vanes U-D	1 byte	DPT_Scaling	5.001		W	T		0%-29% - Pos1; 30%-49% - Pos2; 50%-69% Pos3; 70%-89% - Pos4; 90%-100% - Pos5
		ACxx Control_ Vanes U-D	1 byte	DPT_Enumerated	5.010		W	T		1 - Pos1; 2 - Pos2; 3 - Pos3; 4 - Pos4; 5 - Pos5

	17	ACxx Control_ Vanes U-D Swing	1 bit	DPT_Bool	1.002		W	T	0 – Off; 1 - Swing
	18	ACxx Control_ Vanes U-D Pos1	1 bit	DPT_Bool	1.002		W	T	1 – Set Position 1
	19	ACxx Control_ Vanes U-D Pos2	1 bit	DPT_Bool	1.002		W	T	1 – Set Position 2
	20	ACxx Control_ Vanes U-D Pos3	1 bit	DPT_Bool	1.002		W	T	1 – Set Position 3
	21	ACxx Control_ Vanes U-D Pos4	1 bit	DPT_Bool	1.002		W	T	1 – Set Position 4
	22	ACxx Control_ Vanes U-D Pos5	1 bit	DPT_Bool	1.002		W	T	1 – Set Position 5
	23	ACxx Control_ Vanes U-D +/-	1 bit	DPT_Step	1.007		W		0 - Decrease; 1 - Increase
ACxx Control_ Vanes U-D +/-		1 bit	DPT_UpDown	1.008		W		0 - Up; 1 - Down	
Temperature	24	ACxx Control_ Setpoint Temperature	2 byte	DPT_Value_Temp	9.001		W	T	(°C)
	25	ACxx Control_ Ambient Temperature	2 byte	DPT_Value_Temp	9.001		W	T	(°C)
	26	ACxx Control_ Setpoint Temp +/-	1 bit	DPT_Step	1.007		W		0 - Decrease; 1 - Increase
		ACxx Control_ Setpoint Temp +/-	1 bit	DPT_UpDown	1.008		W		0 - Up; 1 - Down
Filter	27	ACxx Control_ Reset Filter	1 bit	DPT_Bool	1.015		W	T	1 – Reset filter
Lock	28	ACxx Control_ Lock On/Off	1 bit	DPT_Bool	1.003		W	T	0 - Disabled; 1 - Enabled
	29	ACxx Control_ Lock Mode	1 bit	DPT_Start	1.003		W	T	0 - Disabled; 1 - Enabled
	30	ACxx Control_ Lock Set Temp	1 bit	DPT_Start	1.003		W	T	0 - Disabled; 1 - Enabled

NOTE: Object number is only referred to the first AC unit (AC01). In order to get the rest of the AC units object number for each communication object, please use the formula below:

$$AC\ xx\ Object\ Number = (xx-1)*62 +\ current\ Object\ Number$$

On/Off	31	ACxx Status_ On/Off	1 bit	DPT_Switch	1.001	R		T	0 - Off; 1-On
Mode	32	ACxx Status_ Mode	1 byte	DPT_HVACContrMode	20.105	R		T	0 - Auto; 1 - Heat; 3 - Cool; 9 - Fan; 14 - Dry
	33	ACxx Status_ Mode Cool/Heat	1 bit	DPT_Heat/Cool	1.100	R		T	0 - Cool; 1 - Heat
	34	ACxxStatus_ Mode Auto	1 bit	DPT_Bool	1.002	R		T	1 - Auto
	35	ACxx Status_ Mode Heat	1 bit	DPT_Bool	1.002	R		T	1 - Heat
	36	ACxx Status_ Mode Cool	1 bit	DPT_Bool	1.002	R		T	1 - Cool
	37	ACxx Status_ Mode Fan	1 bit	DPT_Bool	1.002	R		T	1 - Fan
	38	ACxx Status_ Mode Dry	1 bit	DPT_Bool	1.002	R		T	1 - Dry
	39	ACxx Status_ Mode Text	14 byte	DPT_String_8859_1	16.001	R		T	ASCII String
Fan Speed	40	ACxx Status_ Fan Speed / 3 Speeds	1 byte	DPT_Scaling	5.001		W	T	33% - Speed 1; 67% - Speed 2; 100% - Speed 3;
		ACxx Status_ Fan Speed / 3 Speeds	1 byte	DPT_Enumerated	5.010		W	T	1 - Speed 1; 2 - Speed 2; 3 Speed 3;
	41	ACxx Status_ Fan Speed Manual/Auto	1 bit	DPT_Bool	1.002	R		T	0 – Manual; 1 - Auto
	42	ACxx Status_ Fan Speed 1	1 bit	DPT_Bool	1.002	R		T	1 – Fan is in speed 1
	43	ACxx Status_ Fan Speed 2	1 bit	DPT_Bool	1.002	R		T	1 – Fan is in speed 2
	44	ACxx Status_ Fan Speed 3	1 bit	DPT_Bool	1.002	R		T	1 - Fan is in Speed 3
	45	ACxx Status_ Fan Speed Text	14 byte	DPT_String_8859_1	16.001	R		T	ASCII String
Vanes Up-Down	46	ACxx Status_ Vanes U-D / 5 pos	1 byte	DPT_Scaling	5.001	R		T	20% - Pos1; 40% - Pos2; 60% - Pos3; 80% - Pos4; 100% – Pos5
		ACxx Status_ Vanes U-D / 5 pos	1 byte	DPT_Enumerated	5.010	R		T	1 - Pos1; 2 - Pos2; 3 - Pos3; 4 - Pos4; 5 – Pos5
	47	ACxx Status_ Vanes U-D Swing	1 bit	DPT_Bool	1.002	R		T	0 – Off; 1 - Swing
	48	ACxx Status_ Vanes U-D Pos1	1 bit	DPT_Bool	1.002	R		T	1 - Position 1
	49	ACxx Status_ Vanes U-D Pos2	1 bit	DPT_Bool	1.002	R		T	1 - Position 2
	50	ACxx Status_ Vanes U-D Pos3	1 bit	DPT_Bool	1.002	R		T	1 - Position 3

	51	ACxx Status_ Vanes U-D Pos4	1 bit	DPT_Bool	1.002	R		T	1 - Position 4
	52	ACxx Status_ Vanes U-D Pos5	1 bit	DPT_Bool	1.002	R		T	1 - Position 5
	53	ACxx Status_ Vanes U-D Text	14 byte	DPT_String_8859_1	16.001	R		T	ASCII String
Temperature	54	ACxx Status_ AC Setpoint Temp	2 byte	DPT_Value_Temp	9.001	R		T	(°C)
	55	ACxx Status_ AC Return Temp	2 byte	DPT_Value_Temp	9.001	R		T	(°C)
Filter	56	ACxx Status_ Filter Status	1 bit	DPT_Bool	1.002	R		T	0 - No Alarm; 1 - Alarm
Lock	57	ACxx Status_ Lock On/Off	1 bit	DPT_Bool	1.003		W	T	0 - Disabled; 1 - Enabled
	58	ACxx Status_ Lock Mode	1 bit	DPT_Start	1.003		W	T	0 - Disabled; 1 - Enabled
	59	ACxx Status_ Lock Set Temp	1 bit	DPT_Start	1.003		W	T	0 - Disabled; 1 - Enabled
Error codes	60	ACxx Status_ Error/Alarm	1 bit	DTP_Alarm	1.005	R		T	0 - No Alarm; 1 - Alarm
	61	ACxx Status_ Error Code	2 byte	Enumerated		R		T	0 - No Error; Any other – check the user manual
	62	ACxx Status_ Error Text code	14 byte	DPT_String_8859_1	16.001	R		T	TO Error; Empty – none

NOTE: Object number is only referred to the first AC unit (AC01). In order to get the rest of the AC units object number for each communication object, please use the formula below:

$$\text{AC xx Object Number} = (\text{xx}-1)*62 + \text{current Object Number}$$